

$$\frac{d^2 y}{dx^2} + q(x) \frac{dy}{dx} = r(x) \leftarrow \text{not quite an ODE.}$$

rewrite this

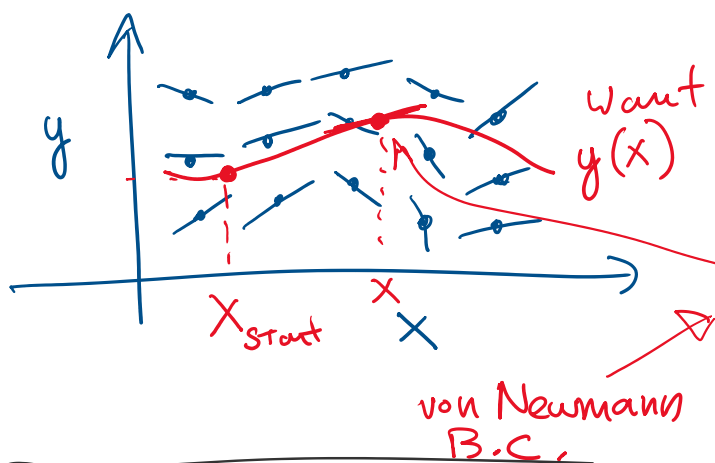
$$\frac{dy}{dx} = z(x)$$

$$\frac{dz}{dx} = r(x) - q(x) \cdot z(x)$$

In general: N -Functions and N -equations

$$\frac{dy_i(x)}{dx} = f_i(x, y_0, y_1, \dots, y_{N-1})$$

$i = 0, \dots, N-1$



want Boundary Conditions
Initial Conditions

$$\frac{dy}{dx}(x_{\text{start}}) = \text{slope}$$

$$y(x_{\text{start}}) = y_s$$

Dirichlet B.C.

von Neumann B.C.

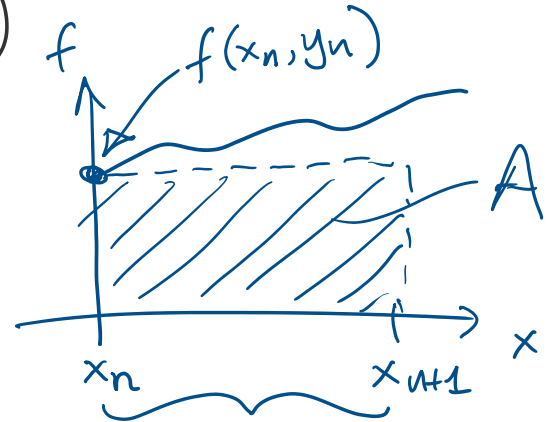
$$\int_{y_0}^{y_1} dy = \int_{x_0}^{x_1} f(x, y) dx$$

y_0 x_0 ...

We want $y(x)$ with a certain accuracy:

$$\frac{dy}{dx} = f(x, y)$$

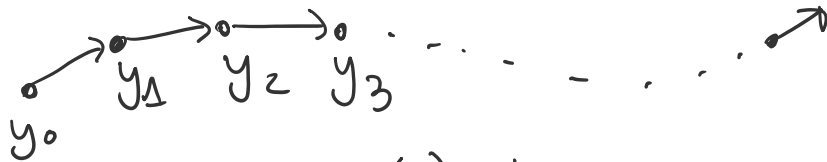
$$\int_{y_n}^{y_{n+1}} dy = \int_{x_n}^{x_{n+1}} f(x, y) dx$$



$$y_{n+1} - y_n = h \cdot f(x_n, y_n)$$

h - step size

$$y_{n+1} = y_n + h \cdot f(x_n, y_n)$$



$$y(x) \approx y_0, y_1, y_2$$

Truncation Error: Error associated with the algorithm or method, and not the precision of the floating point calculation.

" h "

Local Error: Error of one Step

Global Error: Error over a fixed interval.

Δx a global interval

$$\int_{x_n}^{x_{n+1}} f(x, y) dx = \int_{x_n}^{x_{n+1}} [f(x, y_n) + f'(x, y_n) \cdot (y_{n+1} - y_n)] dx$$

$$= h \cdot f(x_n, y_n) + h \cdot (y_{n+1} - y_n) \cdot f'(x_n, y_n)$$

Substitute $y_{n+1} - y_n = h \cdot f(x_n, y_n)$

$$= h \cdot f(x_n, y_n) + (h^2 f(x_n, y_n) f'(x_n, y_n))$$

Local Error of $\mathcal{O}(h^2)$

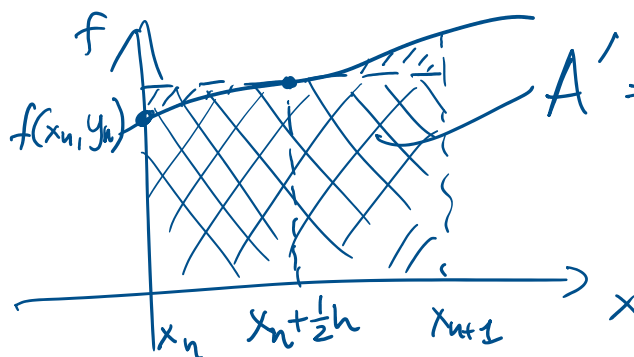
How many Steps $N_{\text{steps}} = \frac{\Delta x}{h}$

Global Error $\Rightarrow \mathcal{O}(h)$

Forward Euler Method

Never use
except in
assignments
😊

Can we do better?



$$A' = h \cdot f(x_n + \frac{h}{2}, y(x_n + \frac{h}{2}))$$

unknown

$$y_{n+\frac{1}{2}} \approx y_n + \frac{h}{2} f(x_n, y_n)$$

Then,

$$y_{n+1} - y_n = h \cdot f(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n))$$

Midpoint Runge-Kutta

Local error: $\mathcal{O}(h^3)$

Local error: $\mathcal{O}(h^3)$
Global error: $\mathcal{O}(h^2)$

4th - Order Runge-Kutta

$$\underline{k}_1 = h \cdot \underline{f}(x_n, y_n)$$

$$\underline{k}_2 = h \cdot \underline{f}\left(x_n + \frac{h}{2}, y_n + \frac{\underline{k}_1}{2}\right)$$

$$\underline{k}_3 = h \cdot \underline{f}\left(x_n + \frac{h}{2}, y_n + \frac{\underline{k}_2}{2}\right)$$

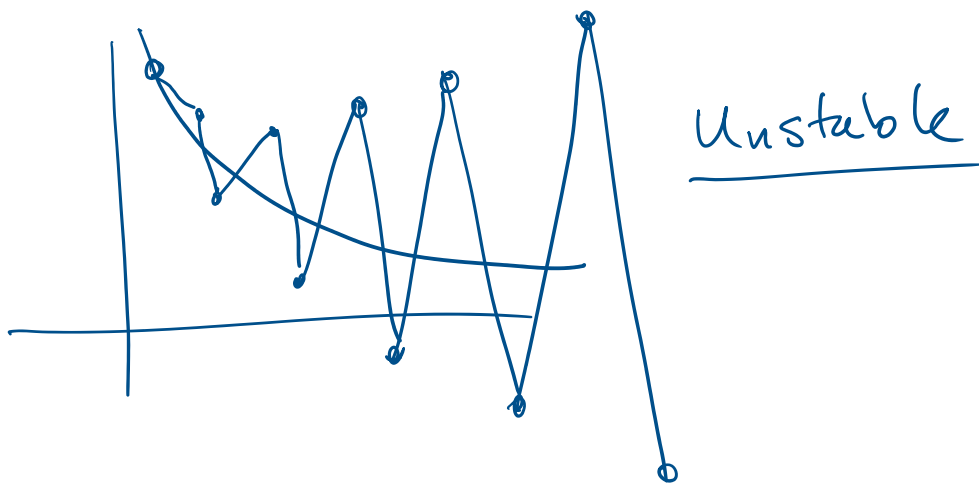
$$\underline{k}_4 = h \cdot \underline{f}(x_n + h, y_n + \underline{k}_3)$$

$$y_{n+1} = y_n + \frac{\underline{k}_1}{6} + \frac{\underline{k}_2}{3} + \frac{\underline{k}_3}{3} + \frac{\underline{k}_4}{6} + \mathcal{O}(h^5)$$

Explicit

$$\underline{y}_{n+1} = y_n + h \cdot \underline{f}\left(\frac{1}{2}(x_n + x_{n+1}), \frac{1}{2}(y_n + \underline{y}_{n+1})\right)$$

Implicit Method



Predator - Prey Verhalten
Lotka-Volterra Model (1920)

Lotka-Volterra Model (11a)

Foxes and Mice
f m

Without foxes the mice population grows without limitation.

$$\frac{\Delta m}{m} = k_m \cdot \Delta t$$

↑ Birth rate (constant)

But if foxes are around then the population reduces proportional to the number of foxes.

$$\frac{\Delta m}{m} = k_m \Delta t - k_{mf} \cdot f \cdot \Delta t$$

$$\Delta m = (k_m \cdot m - k_{mf} \cdot \underbrace{m \cdot f}_{\text{Number of encounters}}) \Delta t$$

$$\frac{\Delta f}{f} = -k_f \Delta t$$

↑ Death rate for foxes

$$\frac{\Delta f}{f} = -k_f \Delta t + k_{fm} m \Delta t$$

$$\Delta f = (-k_f f + k_{fm} f m) \Delta t$$

$$dm = k_m \cdot m - k_{mf} \cdot m \cdot f$$

$$\frac{dm}{dt} = k_m \cdot m - k_{mf} \cdot m \cdot f$$

$$\frac{df}{dt} = -k_f \cdot f + k_{fm} \cdot f \cdot m$$

$$k_m = 2$$

$$k_{mf} = 0.02$$

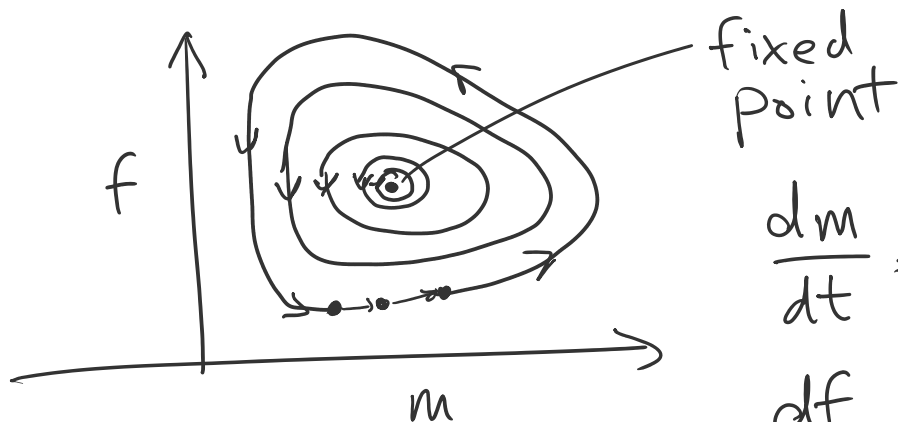
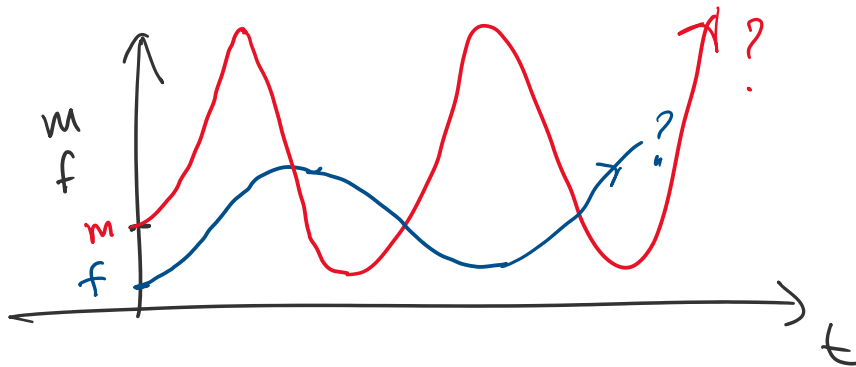
$$k_{fm} = 0.01$$

$$k_f = 1.06$$

$$m(0) = 100$$

$$f(0) = 15$$

2 Plots Please:



$$\frac{dm}{dt} \stackrel{!}{=} 0$$

$$\frac{df}{dt} \stackrel{!}{=} 0$$

?